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Titre : Device for connecting the ends of pipes made of steel by means of an orbital welding process.

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Abrégé :

The invention relates to a device for connecting the ends of pipes, which are already aligned and tack-welded and which are made of steel in particular, by means of an orbital welding process using a welding joint which is formed by the pipe ends and using tools which can be moved about the welding joint in an orbital manner for welding and checking the welding seam. The device consists of guide base plates which can be placed on both sides at each pipe end in the region of the welding point and which can be rigidly clamped to said pipe ends. The guide base plates centrally have a circular recess with a radial opening for the feed-through of the pipes to be welded and for centrally receiving said pipes in the recess. The guide base plates comprise clamping elements for clamping the guide base plates to the pipe ends, said clamping elements being rigidly connected to each guide base plate face facing away from the welding joint, and a frame for receiving the welding and checking tools, said frame being rotatably mounted between the guide base plates on the inner faces facing the welding joint and being centrally pivotal about the pipe ends by at least 360°.

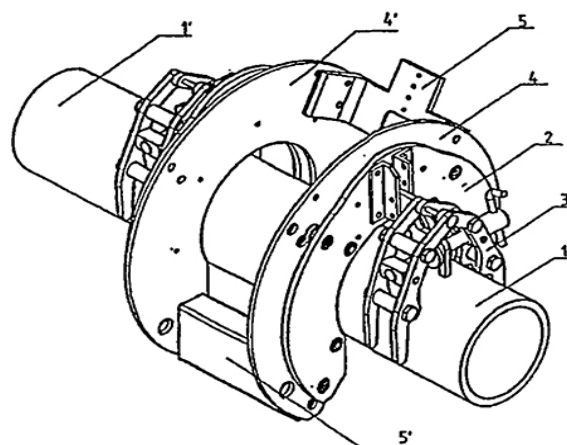


Fig. 1

DEVICE FOR CONNECTING THE ENDS OF PIPES MADE OF STEEL BY MEANS
OF AN ORBITAL WELDING PROCESS

Description

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[001] The invention relates to a device for connecting the ends of steel pipes by means of orbital welding, according to the preamble of patent claim 1.

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[002] In particular, the invention relates to the welding of pipes, which may for example have wall thicknesses of 2 to 20 mm and a diameter of 60 to 1600 mm and which are connected to each other to form pipe lines by means of different welding procedures such as laser beam welding, combined laser beam/laser arc welding or electric arc welding. In the following, pipes are understood as circular pipes as well as hollow profiles with different cross sections.

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[003] The orbital welding of pipes is generally known for example from DE 103 34 446 A1. Here an orbital welding device for connecting two pipe ends is disclosed, wherein the device is attached and clamped to a first pipe end and the second pipe end is brought into welding position in so as to confront the first pipe end. By means of two welding heads which are offset relative to each other by 180° and which are guided pivotal about an axis, a 360° circular welding seam can be achieved. A disadvantage is that two welding heads are required in order to weld the pipe along the entire circumference.

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[004] A further orbital welding device is known from WO 2005/0-56230 A1 in which a combination of metal protective gas welding and laser arc welding is used. This so called laser MSG hybrid welding is characterized in that the electric arc and the laser beam are arranged at a defined distance to each other and a higher gap bridging capacity can be achieved compared to a pure laser beam welding process.

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The device includes a guide ring, which can be oriented relative to the end of the first pipe. The orientation occurs via multiple clamping screws, which are arranged along

the guide ring circumference and by means of which the distance of the guide ring to the pipe surface can be adjusted. The guide ring serves for guiding an orbital carriage, which can be moved thereon and which can accommodate further components for process monitoring and welding seam checking. The described
5 device is used in mobile application for orbital welding of pipes to pipelines.

[005] A disadvantage of this device is the complex construction with guide rings that are closed about the pipe and the elaborate alignment and centering of the pipe ends. Especially the centering requires great effort in the case of large pipe
10 diameters and requires additional centering devices in the device having correspondingly great holding forces in order to ensure a geometrically stable welding groove during the welding. This makes the device very heavy and its use in mobile application is very difficult.

[006] In addition the sequence of the welding process is very complex in which the pipe ends have to be inserted into the device and centered and subsequently the welded pipe has to be moved lengthwise out of the device.
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[007] In summary, no industrially applicable orbital guiding system exists in the state of the art that is optimally adjusted to the demands regarding quality and
20 economical efficiency of the orbital welding.

[008] It is an object of the invention to set forth a device for connecting the ends of steel pipes by means of orbital welding, which overcomes the described
25 disadvantages, i.e., which can be cost-effectively produced and flexibly used with small time investment.

[009] This object is solved starting from the preamble of claim 1 in connection with its characterizing features. Advantageous refinements are the subject matter of
30 dependent claims.

[0010] The teaching of the Invention includes a device for connecting the ends of pipes, in particular steel pipes, by means of orbital welding, which have already been oriented and tack seam welded, with a welding groove which is formed by the ends of the pipes and tools which can be orbitally moved about the welding groove for welding and testing the welding seam, the device being characterized in that it includes guide base plates which can be attached and securely clamped onto the pipe ends on both sides on the respective pipe ends in the region of the welding site, wherein the guide base plates have a central circular recess with a radial opening for centered reception of the pipes to be welded in the recess, with clamping elements which are fixedly connected on the respective side of the guide base plates, which sides face away from the welding groove, for clamping the guide base plates with the pipe ends, and with a frame for receiving the welding and testing tools, which frame is arranged so as to be pivotally supported between the guide base plates on the inner sides and is centrally pivotal about the pipe ends by at least 360°.

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[0011] For welding, the device is simply placed on the pipe ends with a radial distance to the pipe ends and with the guide base plates symmetrical to the welding groove, and clamped with the pipe ends using the clamping elements which are securely connected with the guide base plates. For this, the diameter of the circular recess in the guide base plates is greater than the diameter of the pipe ends to be received. Advantageously this also enables using the device also for welding of different pipe diameters. The pipe to be welded is located in the circular recess of the guide base plates, wherein the radial distance between guide base plate and pipe is adjusted so that the pivot frame, which is pivotally arranged between the guide base plates with tool holders for welding and testing tools, extends centrally about the longitudinal axis of the pipe to be welded.

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[0012] The device according to the invention overcomes the disadvantages of the known orbital welding devices on one hand by a very simple and with this cost-effective construction, and on the other hand also in that this device is used advantageously for already aligned, i.e., centered and tack seam welded pipes.

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[0013] Decoupling the centering and the tack welding of the pipe ends from the actual orbital final welding significantly simplifies the construction of the device and renders it more flexible, i.e., better suited for mobile applications.

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[0014] With the proposed device the circumferential seam can further be welded over 360° with only one welding head.

[0015] Advantageously laser beam welding is used for the joining of the pipes.

10 For this a raw beam generated by a laser beam source is conducted via an optical fiber to an optic fastened on the carriage. This optic forms the laser beam and conducts the laser beam onto the joint of the two pipes. Advantageously an angled optic is used for this purpose, wherein the collimation of the laser beam is 150mm and the focusing 200mm. Further an additional so called LWM sensor (Laser
15 Welding-Monitor) is arranged on the optic, which serves for detecting the following parameters:

- emitted plasma glow
- back-reflected laser radiation
- reflected laser power on the beam splitter

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[0016] The reason for using an angled optic is to reduce the work area required by the optical fiber. The optical fiber has a large bending radius and would strongly increase the required work area for the circumferential movement. By using an angled optic the optical fiber can be installed and connected in the direction of the
25 longitudinal axis of the pipe. The feed movement of the optic occurs via two feed axes, which for an accurate positioning of the process in Y-direction (longitudinal relative to the pipe axis) and Z-direction (in radial direction relative to the pipe surface) are advantageously constructed as ball screw transmission.

30 **[0017]** For detecting a welding joint, in particular an edge offset and gap, an advantageous refinement of the invention provides for detecting the line generated

by a line laser transverse to the joint by a camera. The thus detected values are used for the seam programming. The laser line is detected by a camera software and influences via a position calculation the vertical and lateral adjustment of the optic. Subsequent to the welding process the camera is used for determining a topography of the seam. Like the optic the camera and the linear laser are arranged centrally between the two pivot brackets on the carriage and are guided about the pipe with the circumferential movement.

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[0018] For determining inner welding defects two ultrasound testing probes are guided about the pipe so as to trail the welding head. One of each of the welding heads is arranged on either side of the welding seam. The testing probes themselves are arranged pivotal as cylinders and advantageously function without requiring coupling means. They are arranged at a distance to the joint which distance can be adjusted via axes, and are kept in contact with the pipe via spring tension. For different pipe diameters however a height adjustment is also possible via axes. Like the optic and camera the ultrasound testing probes are also arranged centrally between the two inner plates and are moved together with the inner plates about the pipe.

20 [0019] The device is operated via an external control via which the laser system and the hardware can be controlled. It also detects and analyzes all data of the camera of the ultrasound testing probes and the LWM sensor situated on the optic. A software is used to determine and initiate the exact program sequence.

25 [0020] In addition to the tools required for the actual welding process further tools or components required for the welding process, for supporting the welding process or for subsequent manufacturing steps can be guided by means of the carriage. This can for example be a seam tracking system or measuring means for destruction-free quality control of the welding seam by way of seam measurement or
30 defect detection. By means of a system, which is moved ahead of the welding

process, the welding groove can be detected and the subsequent welding process can be adjusted in its position.

5 **[0021]** By means of for example optical systems a quality control of the welding seam is also possible.

[0022] Fig. 1 illustrates the basic construction of the device according to the invention. It includes the two circular guide base plates 2, which are provided with a radial opening in order to be able to attach them onto the pipes 1, 1' to be joined. The inner circular ring diameter is greater than the diameter of the pipes 1, 1' to be welded in order to be able to perform an accurate alignment via the radial clearance for a centric circumferential movement of the welding and testing tools. For fastening the device on the ends of the pipes 1, 1' clamping elements 3 are arranged on the outer welding groove-averted sides of the guide base plates 2, and are used to clamp the two guide base plates 2 with a respective pipe end via clamping elements 3.

[0023] A circular ring-shaped pivot bracket 4, 4', which is also provided with a radial opening, is pivotally guided on each of the inner welding groove-facing sides of the guide base plates 2, so that the pivot brackets can also perform a circular movement along the guide base plates 2 about the pipes 1, 1'. The pivot brackets 4, 4' are rigidly interconnected to form a pivot frame via tool holders 5, 5', wherein all components for joining and testing are mounted on the tool holders 5, 5'.

[0024] Figure 2 shows a schematic sectional view of the ring guide of the pivot brackets or the pivot frame. The circular ring-shaped guide base plate 2 is attached to and clamped on the pipe 1 with the aid of the clamping elements 3. Via the radial clearance between the outer diameter of the pipe 1 and the inner diameter of the guide base plate 2 the device can be exactly centrically aligned relative to the longitudinal axis of the pipe 1. In order to enable a circular movement of the pivot brackets 4, 4', the pivot brackets are advantageously guided orbitally pivotal via a circular guide rail 6 arranged respectively between the guide base plates 2 and pivot

brackets 4, 4'. The guide rails 6 are arranged on the pivot brackets and are each guided via guide rollers 7, which are arranged on the outer and inner surface of the guide rails 6, and are themselves connected with the guide base plates 2.

5 [0025] For driving the circumferential movement of the pivot frame, a sprocket and a drive motor (here not shown) are arranged according to the invention on both sides respectively between pivot bracket 4, 4' and guide base plate 2. The two sprockets are fastened on the pivot brackets 4, 4' and also perform the circumferential movement. The motors are connected with the guide base plates 2
10 and transmit the rotational movement via pinions to the sprockets.

[0026] In an advantageous refinement of the invention, a transmission consisting of a planetary gear system and a worm gear is arranged between the motor and the pinion. The transmission enables a continuous starting and ending of
15 the rotational movement.

[0027] Figure 3 shows a schematic view of the device attached to the pipe ends taken along the longitudinal axis of the pipe with mounted welding and testing tools on the tool holders 5, 5' arranged between the pivot brackets 4, 4'. For reasons
20 of clarity only the rear pivot bracket 4 and the welding and testing tools, which are fastened thereon via the here not shown tool holders 5, 5', are shown in this view.

[0028] On the pivot bracket 4 a laser welding device 8 is arranged which can be displaced along different axes, and which includes a welding head 9 and actuating
25 devices for radial height adjustment 10 and for positioning in longitudinal pipe direction 11, with which actuating devices the laser beam 12 can be exactly aligned relative to the welding groove of the pipes 1, 1' to be interconnected.

[0029] For programming the required seam geometry and with this for
30 controlling the laser (for example positioning, power), the geometry of the welding joint, in particular edge offset and gap, is detected by a camera 14 by means of a line

(here not shown) generated by means of a line laser transverse to the welding groove.

[0030] The thus detected parameters are used for the seam programming. The
5 laser line is detected by a camera software and influences via a position calculation
the height and lateral adjustment of the optic of the welding head 9. Line laser 13 and
camera 14 are provided with an actuating device 15 for height and angle adjustment.

[0031] For determining errors in the welding seam directly after the welding,
10 two ultrasound testing heads 16 are arranged on a further here not shown tool holder
so that they test the welding seam from both sides. The ultrasound testing probes 16
are arranged pivotal and can be radially adjusted by means of further actuating
devices 17, 18 in height and along the longitudinal direction of the pipe relative to the
welding seam to be tested. The ultrasound testing probes 16 are preferably suited for
15 testing without requiring coupling means.

List of reference signs

Nr.	Designation
1, 1'	Pipes
2	Guide base plates
3	Clamping elements
4, 4'	Pivot brackets
5	Tool holder welding head
5'	Tool holder testing tools
6	Guide rails
7	Guide rollers
8	Laser welding device
9	Welding head
10	Actuating device for radial height adjustment
11	Actuating device for positioning in pipe longitudinal direction
12	Laser beam
13	Line laser
14	Camera
15	Height and angle adjustment
16	Ultrasound testing heads
17	Actuating device for radial height adjustment
18	Actuating device for positioning in pipe longitudinal direction

Patent claims

1. Device for connecting ends of already aligned and tack seam welded pipes (1, 1') in particular made of steel by means of orbital welding with a welding groove which is formed by the pipe ends and tools which can be moved orbitally about the welding groove for welding and testing the welding seam, characterized in that the device comprises guide base plates (2) which can be attached to and securely clamped to the pipe ends, wherein the guide base plates (2) have a central circular recess with a radial opening for passage of and central reception of the pipes (1, 1') to be welded in the recess, with clamping elements (3) for clamping the guide base plates (2) with the tube ends, said clamping elements (3) being securely connected to the sides of the guide base plates (2) which face away from the welding groove and with a frame for receiving the welding and testing tools, said frame being pivotally arranged on the inner sides facing the welding groove between the guide base plates (2), said frame being pivotal about the pipe ends centrally by at least 360.
2. Device according to claim 1, characterized in that the frame is made of pivot brackets (4, 4') and of tool receptacles (5, 5') for the welding and testing tools, which tool receptacles connect the pivot brackets (4, 4').
3. Device according to claims 1 and 2, characterized in that between the guide base plates (2) and the pivot brackets (4, 4') respectively a circular guide rail (6) is arranged on which the pivot brackets (4, 4') are supported for orbital pivoting about the pipe (1, 1').
4. Device according to claim 3, characterized in that the pivot brackets (4, 4') are supported on the guide rails (6) via guide rollers (7).
5. Device according to one of the claims 1 to 4, characterized in that laser welding heads, protective gas welding heads and/or hybrid welding heads (9) are mounted on the tool holders (5, 5').

6. Device according to one of the claims 1 to 5, characterized in that a system for destruction free welding seam testing is mounted as testing tool.

5 7. Device according to claim 6, characterized in that the system for destruction free welding seam testing is an ultrasound testing device.

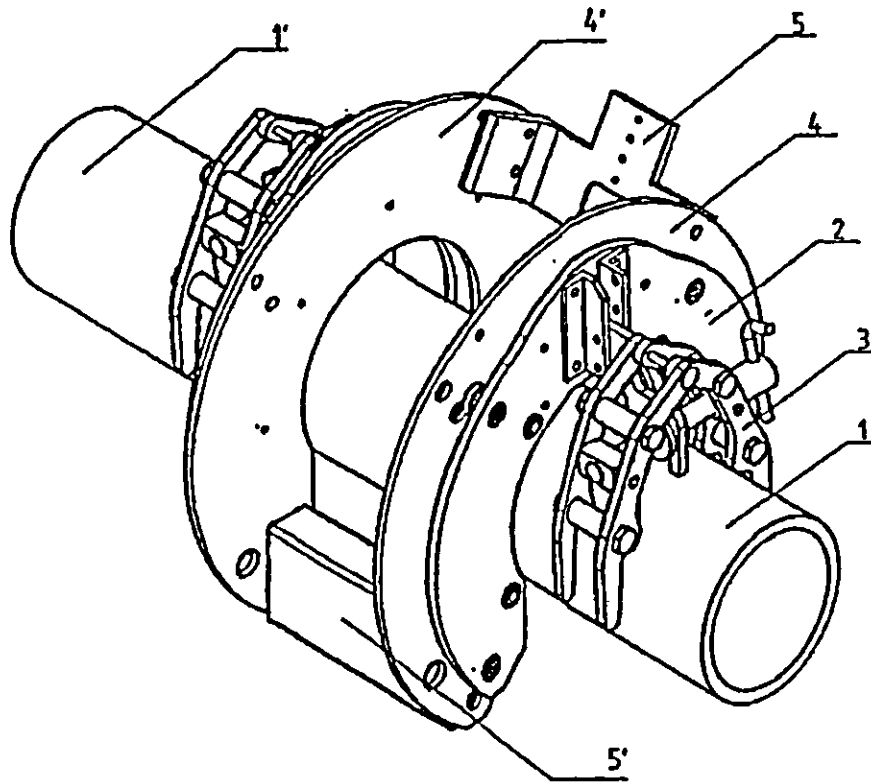
8. Device according to claim 7, characterized in that the ultrasound testing device includes at least two ultrasound testing probes (16) which can be attached on the pipe ends on both sides of the welding seam.

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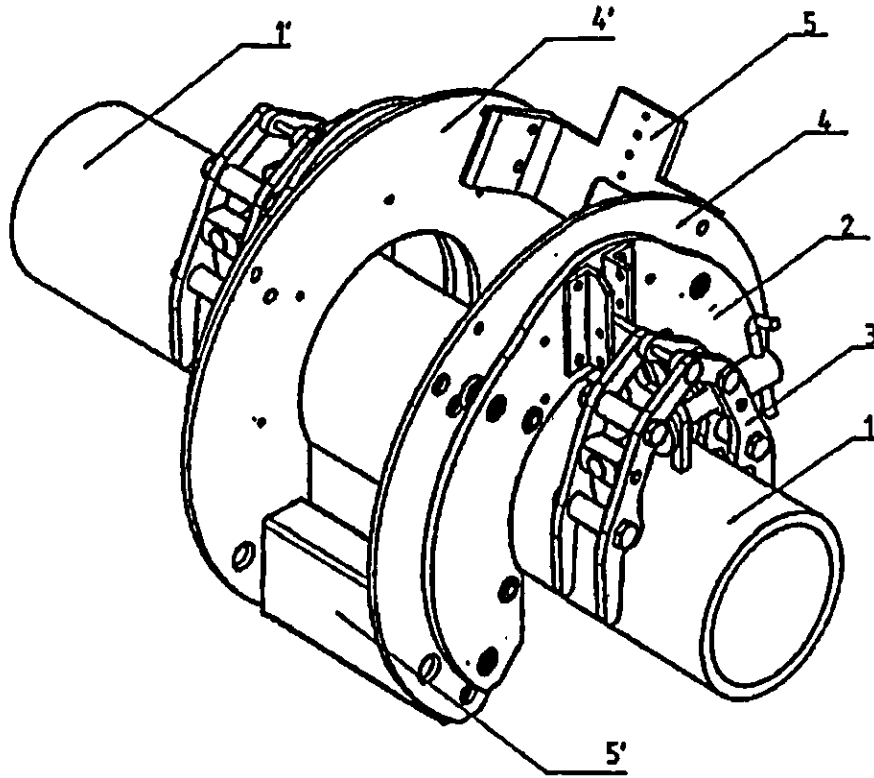
9. Device according to one of the claims 1 to 8, characterized in that beside the welding and testing tools further tools are arranged on the tool holders.

15 10. Device according to claim 9, characterized in that the further tools include one or more additional welding heads, a seam geometry detection system and/or a seam tracking system.

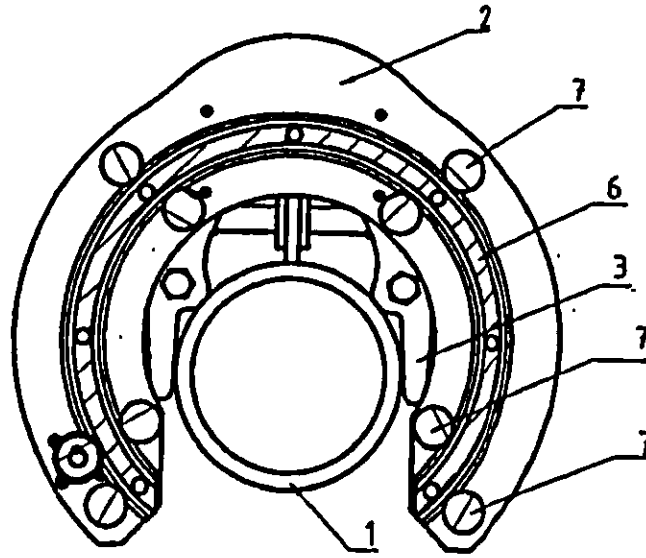
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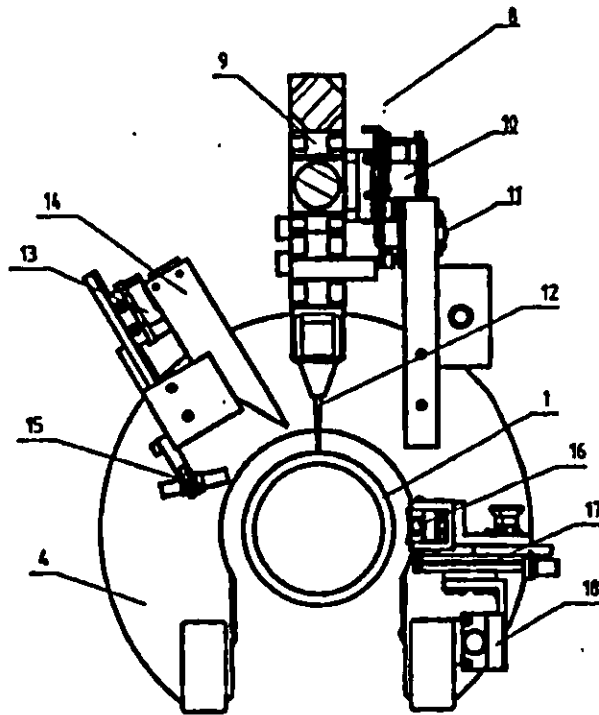
Figur 1



Figur 1



Figur 2



Figur 3